

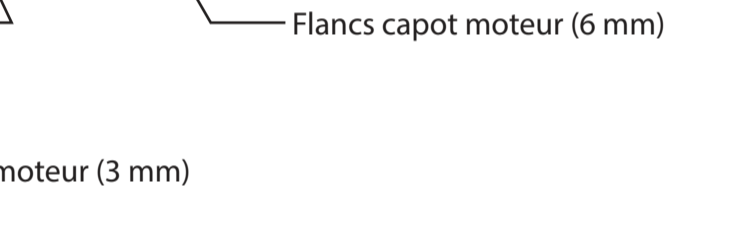
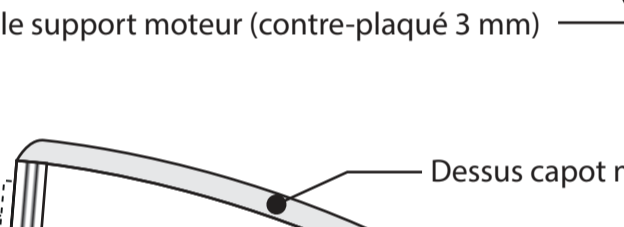
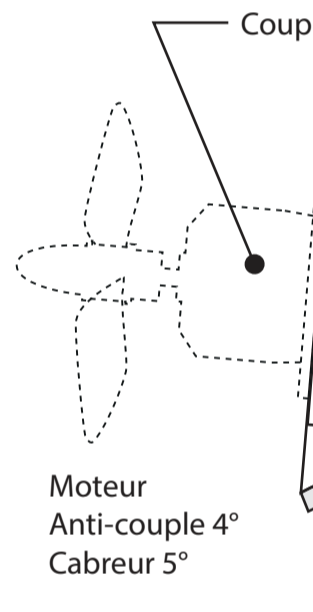
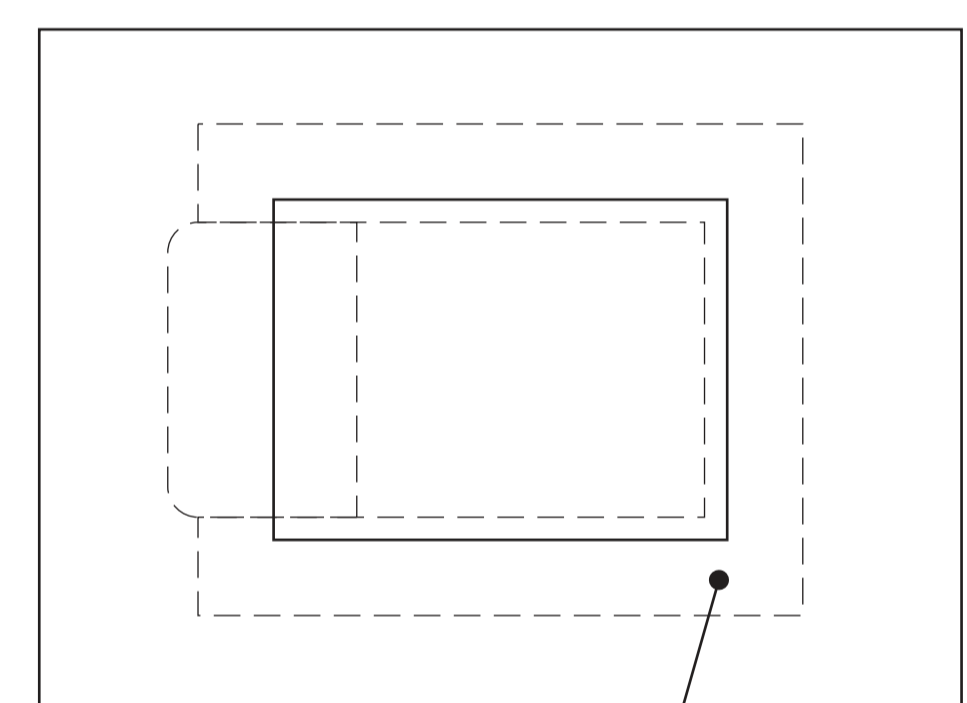
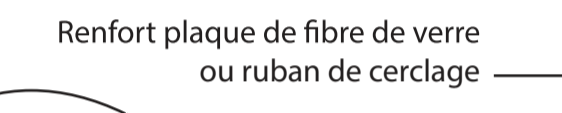
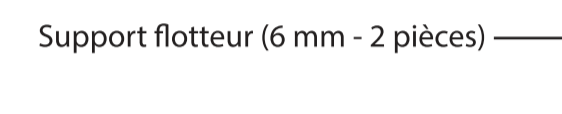
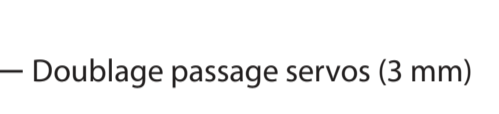
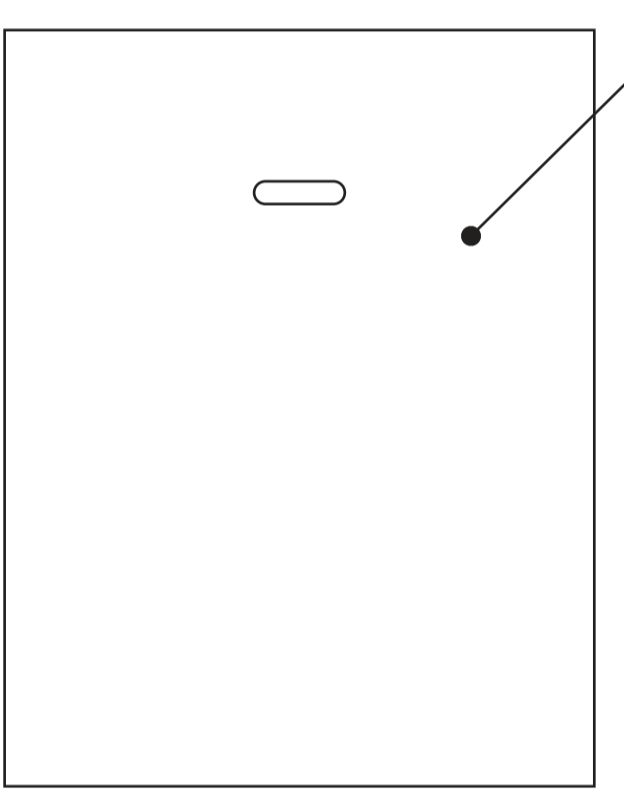
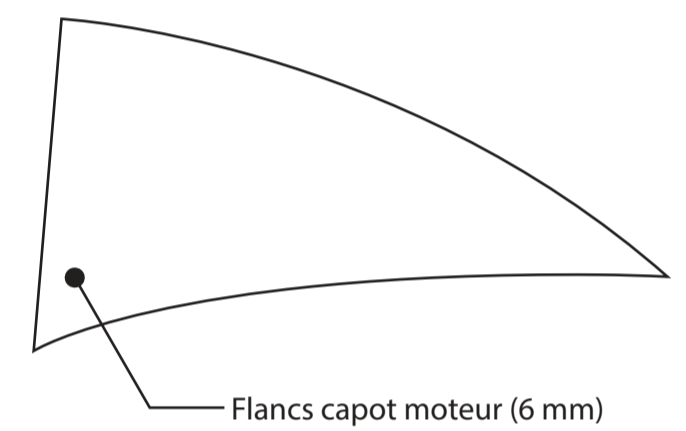
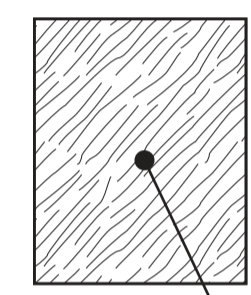
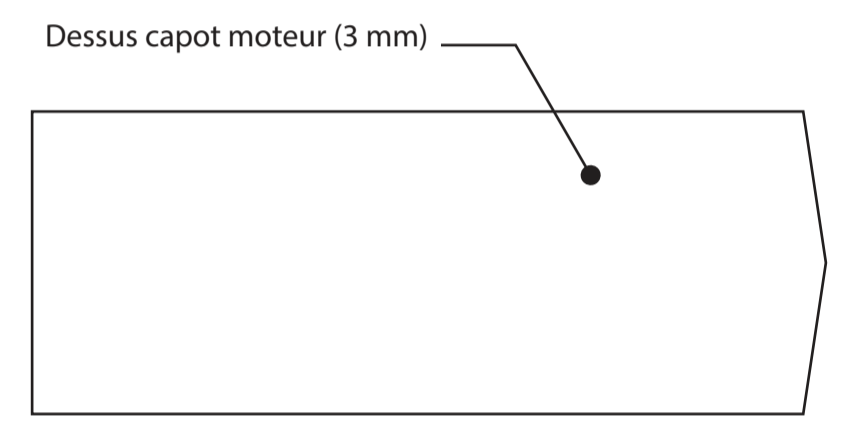
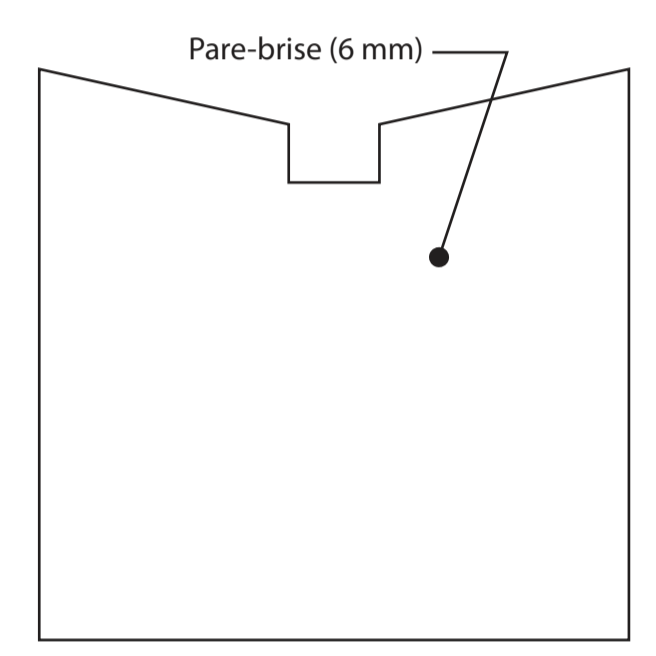
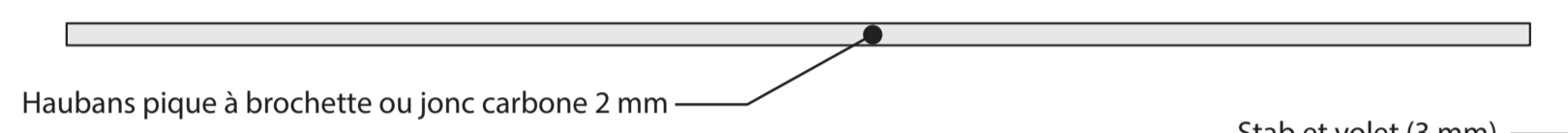
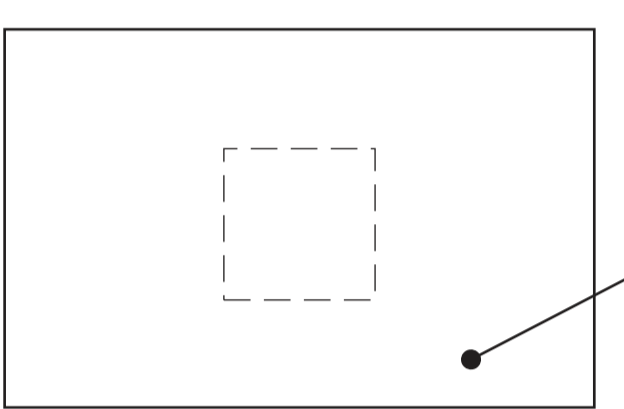
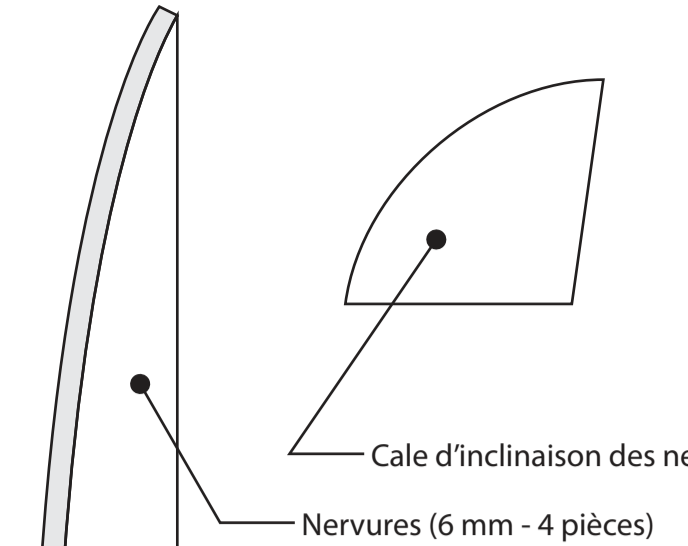
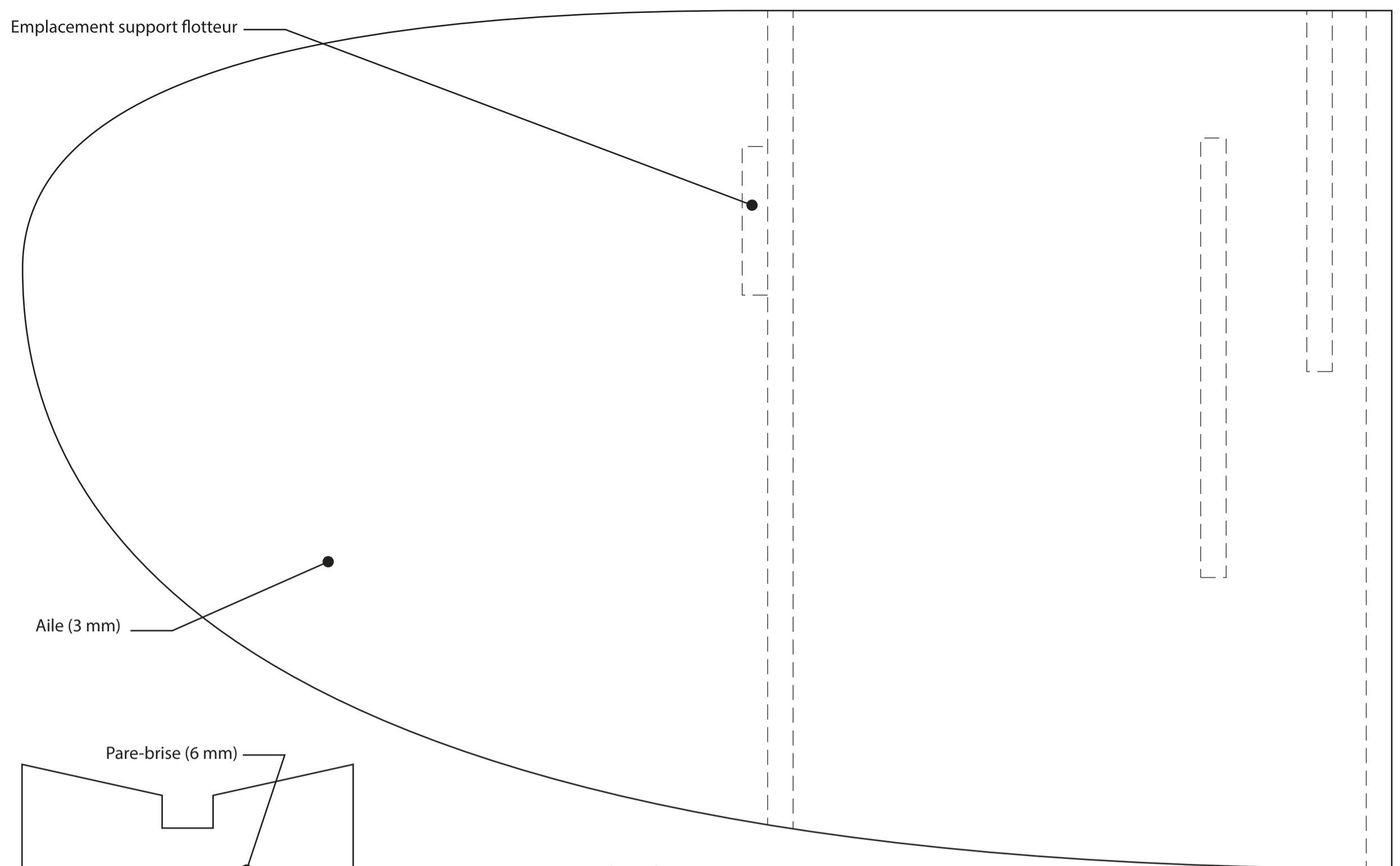
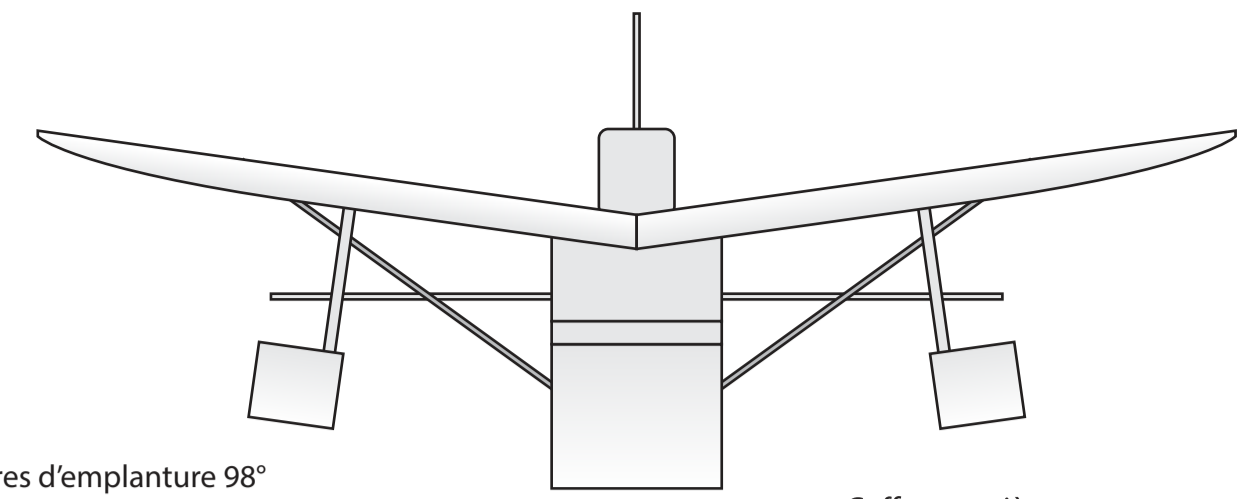
JUPITER DUCK

Conception : Thomas Buschwald (2016)
Retracé par Laurent Berlivet (2017)

Caractéristiques	Equipements
Envergure : 64 cm environ	Moteurs : 15 à 20 g 1700 kV
Longueur : 58 cm environ	Contrôleur : 6 à 15 A BEC
Surface : 10,8 dm ² environ	Hélice : 7"x5"
Masse : 160 à 250 g	Pack prop : Lipo 2S 450 à 600 mAh
Charge alaire : 14,8 à 24 g/dm ²	Servos : 2 x 6 à 9 g
Matériau : Depron 3 et 6 mm	Radio : 3 voies

Réglages
Centrage : 48 mm du bord d'attaque
Tangage : + 20 mm - 20 mm
Lacet : 25 mm de chaque côté

http://www.jivaro-models.org/jupiter_duck/page_jupiter_duck.html



Centre de gravité : 48 mm du bord d'attaque

