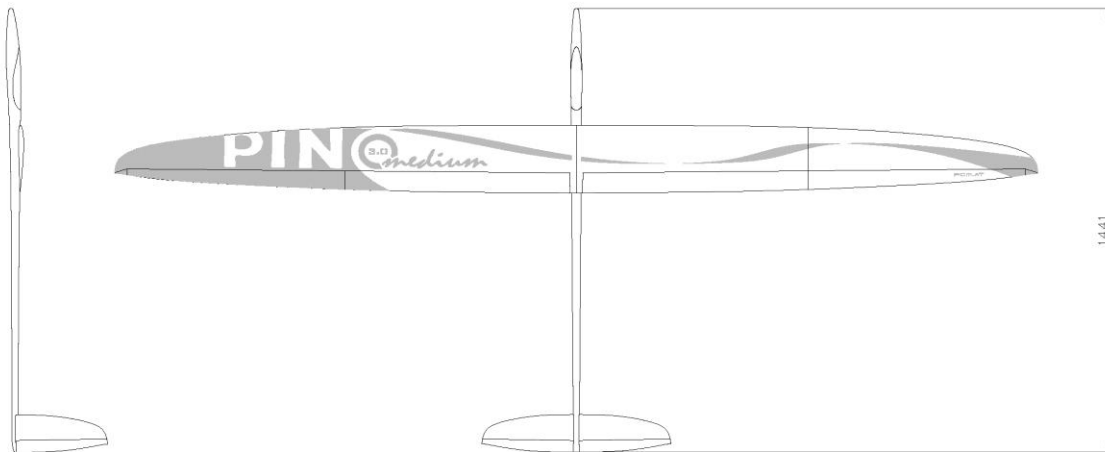
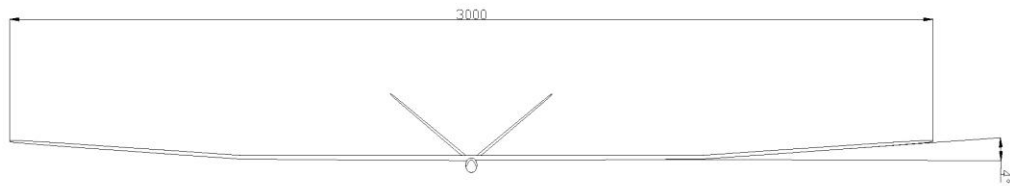


Wing span [mm]:	3000
Wing area [dm <sup>2</sup> ]:	54,7
Aspect ratio:	16,6
Take-off weight [g]:	from about 1830-2710g
Wing loading:	31,6-47,5g/dm <sup>2</sup>
Airfoil:	MP1-1,66/7,6 to MP5-1/5 5 Modern F3b-F3f airfoils



## BUILDING INSTRUCTION

Allround fun glider PINO 3.0 E-Version

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**DATA**

**1. Kit – contents**

- Fuselage + canopy
- Wing
- Elevator
- Lever for controlling ailerons, 2 pc.
- Lever for controlling flaps, 2 pc.
- Bowden pushrods for Elevator and Rudder 2 pc.
- M2.5 screw rod for controlling ailerons, 4 pc.
- 10x lever connectors M2,5
- M4 metal screws for fixing wing, 4 pc.
- M4 nylon screws for fixing wing, 4 pc.
- Spring-loaded contacts 4 pairs
- Gap covers for aileron, flap, elevator, rudder
- 12mm carbon rod wing connectors, 2 pc.
- 12mm steel rod wing connectors, 2 pc.
- 6mm carbon rod elevator connector, 2 pc.
- 2mm carbon rod for elevator, 4 pc.
- Twisted servo lead



Connectors / ballast:

	<b>Segler / Glider</b>	<b>Elektro</b>
<b>Slope</b>	2x carbon rod 2x steel rod 2x long steel rods	2x carbon rod 2x steel rod 2x long steel rods
<b>Medium</b>	2x carbon rod 2x steel rod	2x carbon rod 2x steel rod
<b>Ultralight</b>	2x carbon tubes 2x steel tubes	2x carbon tubes 2x steel tubes

**2. What else do you need:**

- Epoxy-glue (for example UHU 300 endfest or Pattex Stabilit)
- Super glue (runny)
- Electrical equipment (On/Off-switch, cables, plug...)
- Electronic equipment
- Shrinking tube...

**3. Electronic equipment**

- Servo ailerons: - KST DS 135 MG
- Servo flaps: - KST DS 125 MG
- Servo rudder and elevator: - KST X08 V5

Receiver: - for 4 wing servos, rudder and elevator

**Power Set**

- Tenshock EDF TS-EZ1515 - 13T - 4pol 4200KV with Micro Edition 5:1NL
- 1300mAh 3S Wellpower
- Speed Controller 50A
- Prop GM Reisenauer 14x7 (2,4kg Thrust!). Prop fits great to the fuselage.
- RFM Spinner d=28mm with offset 0°

## ASSEMBLING THE MODEL

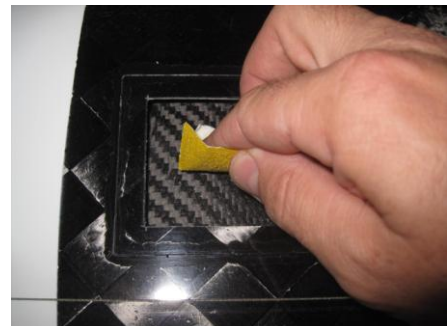
### 4. WING



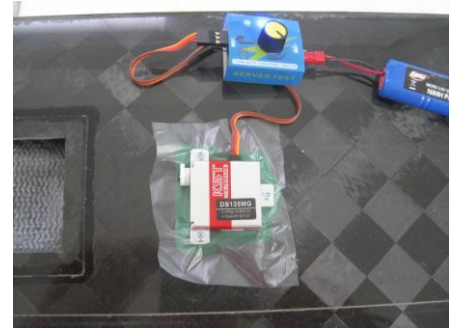
#### 4.1 Controlling flaps and ailerons

##### Fixing the servos

First of all, prepare the **surfaces** which will be glued. **Grind** them with a rough paper (about 80-40 grain size).



Then, set the servo to the **zero position** and **screw it to the frame**. The screwing is important, because if you screw the servo after gluing it into the wing, tension will occur and the surface of the wing will get wavy.



The **lever lengths:**

**Aileron: 8mm** (first hole of the smaller lever of the KST servos.)

**Flaps: 10mm** (first hole of the stronger lever of the KST servos.)

The length is measured from rotation center to hole center.

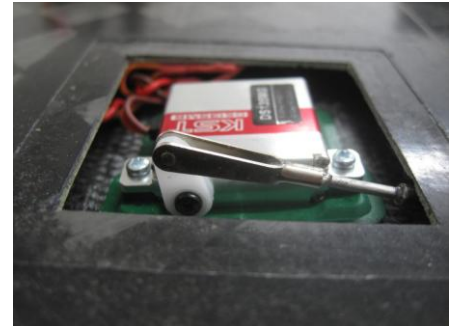


**Flap servo:**

Set the **servo** to its **zero position** and let the **lever** show a little bit **to the front**. So you get more break deflection.

**Aileron servo:**

Let the lever in **rectangular** position.



Verify the **free movement** of all the parts.



It will be necessary, that you **optimize the lever connector** as shown in the pictures besides.

It has to be done in different ways for the flaps and for the ailerons.



**Aileron servo**

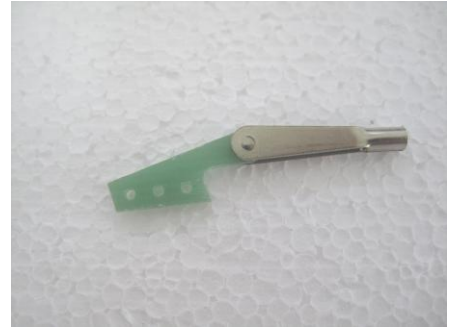
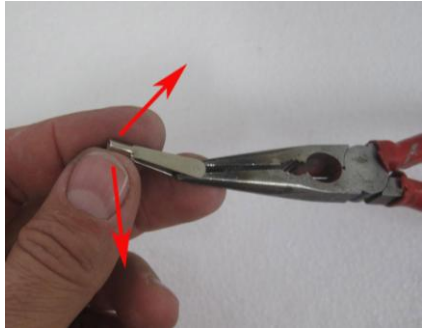


**Flap servo**

Prepare the parts for gluing the control levers into the wing. **Grind all gluing surfaces**, the slot of the control surfaces and the levers themselves.



The **bolt of the lever connector** has sharp edges that are bigger than the bolt diameter. You should **remove these edges**, before you put the connector into the lever. It is easy to clean that bolt with nose pliers. Grab the bolt with the nose pliers and move the connector up and down about 3 times as shown in the picture. Repeat this that often until the connector is able to **move in the lever hole without a lot of friction**.



Before you glue the lever into the control surface, **fix the connector to the lever**.

The short lever is for the aileron and the long lever for the flaps.



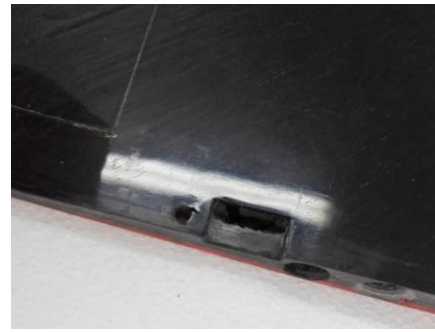
You can use **runny super glue** to fix the levers. This kind of bonding will be strong enough for the forces occurring.



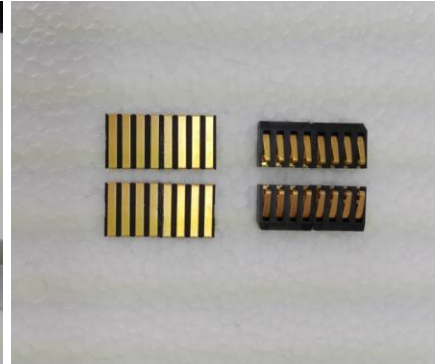
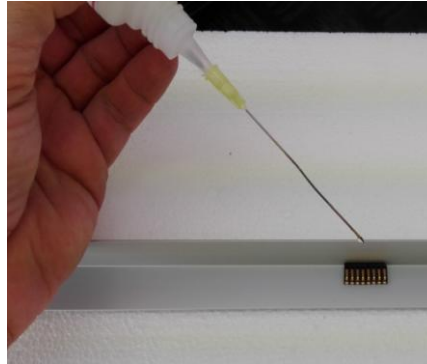


**Cable mounting:**

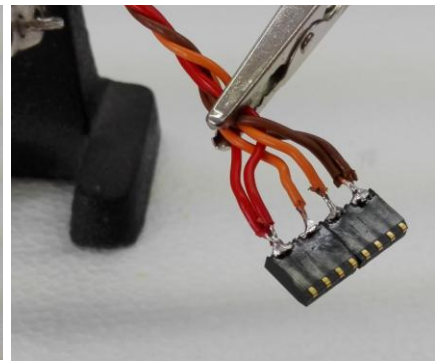
**Mill a hole** into the preformed space for the contacts. Make the hole big enough, so that the **contacts will not touch the carbon**.



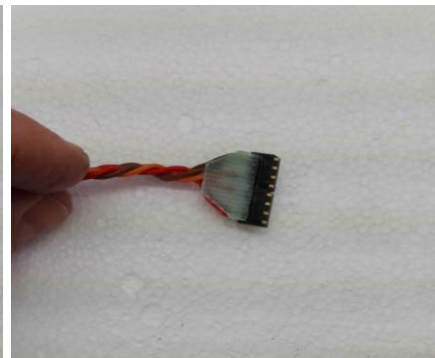
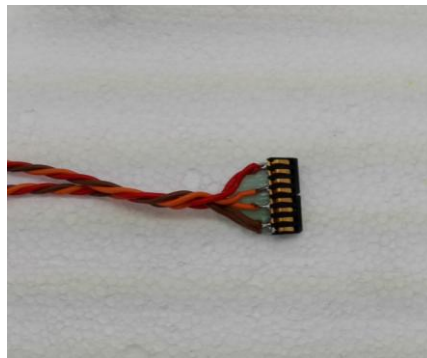
We now use **2 pairs of contacts** for a redundant connection. Glue the contacts together.



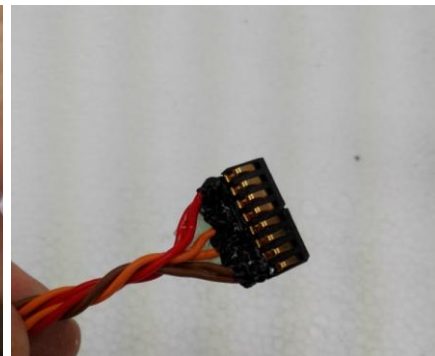
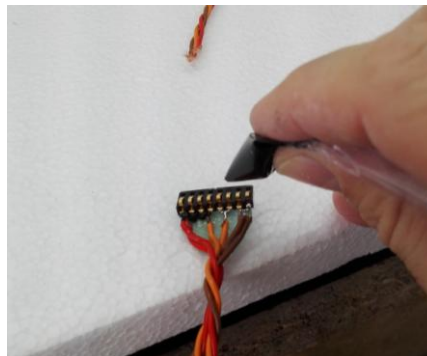
Connect the cable as shown and solder the ends to **BOTH** of the contacts. So you get a safe, redundant connection.



In order to secure the soldered wirings you should glue a **piece of plywood or GFR** to it.



It is very important to **insulate all the contacts** that could touch the carbon. We use "Plasti Dip" for such purposes.



Make sure that the contact **fits easily** into the free space, which is provided for the contact, without putting any force on the soldered areas.

Before you fix the contact with a drop of runny super glue, check if **all the servos work well**.



Now you can stick the **seals over the gaps**.

Use the broad ones for the wing and the narrow ones for the elevator.





## 5. FUSELAGE – electric version

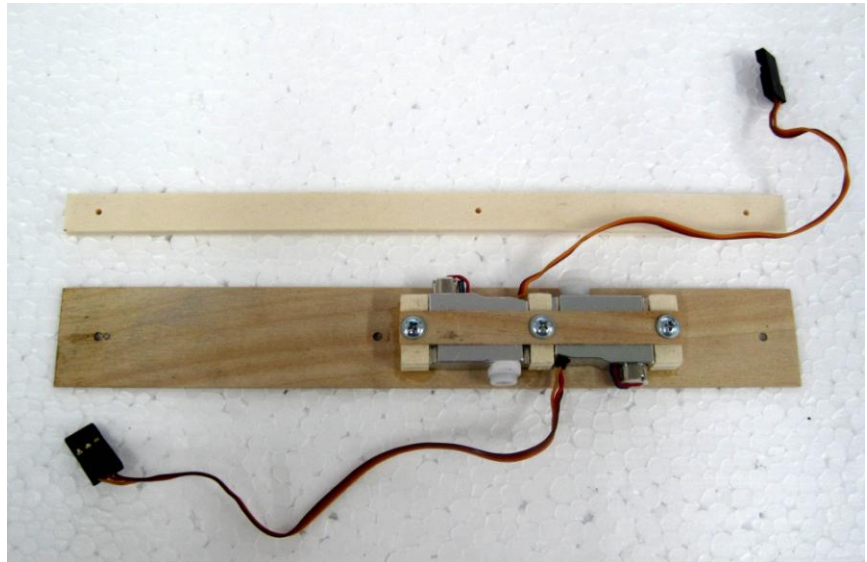
### 5.1 Servoboard

All necessary **holes** are already **pre-milled**.

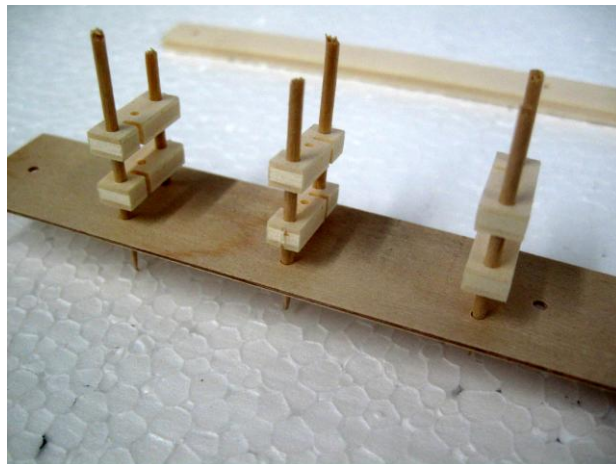
(Here a Pino 2.5m fuselage is shown. Some of the following pictures are taken from the Pino 2.5. The difference is very little)



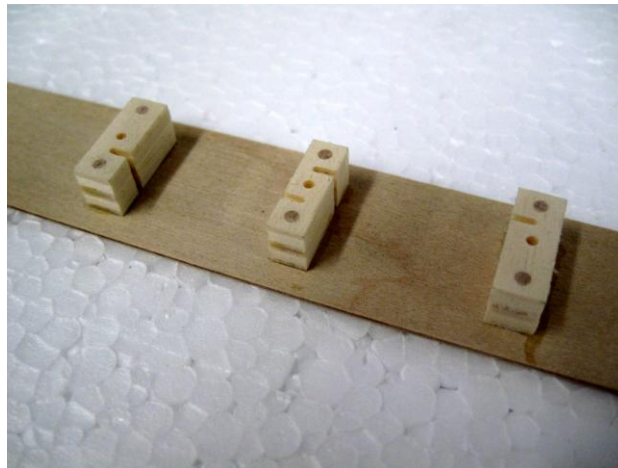
CNC milled **wood parts** are included in the kit for mounting the **KST X08 V3**.



Set the parts together with **toothpicks**.

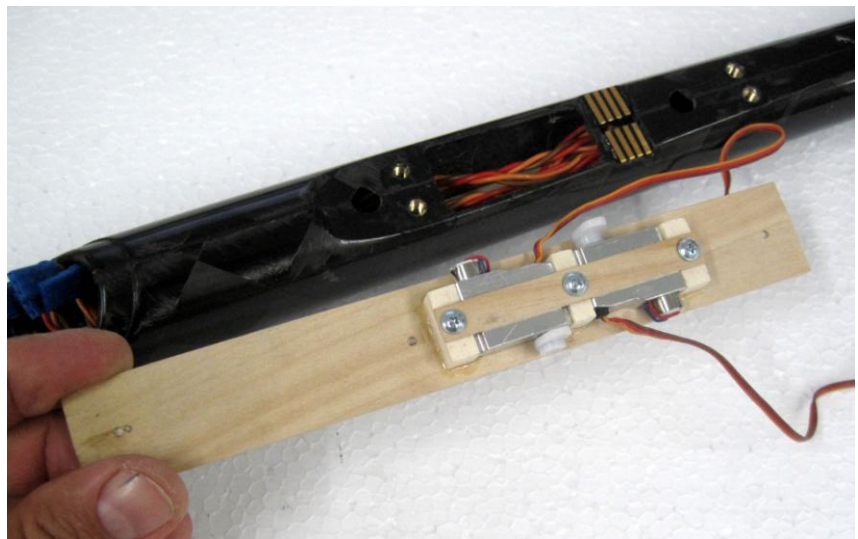


**Glue** everything with **super glue** and then cut off the toothpicks.



**Mount the servos** as shown in the picture.

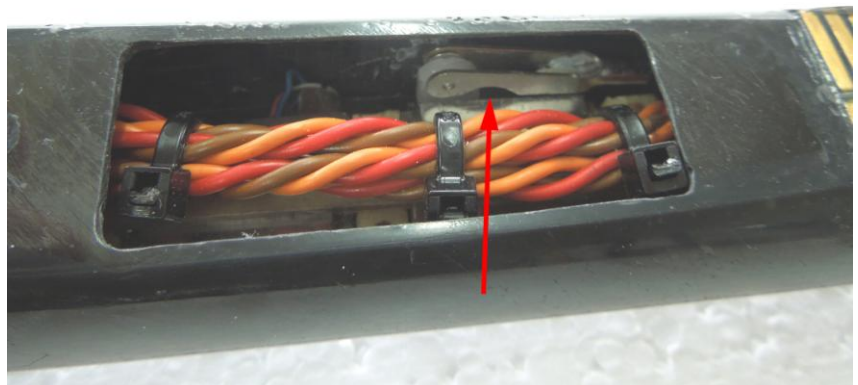
**Lengthen the servo cables**, so they reach the receiver comfortably.



The **lever lengths** are:

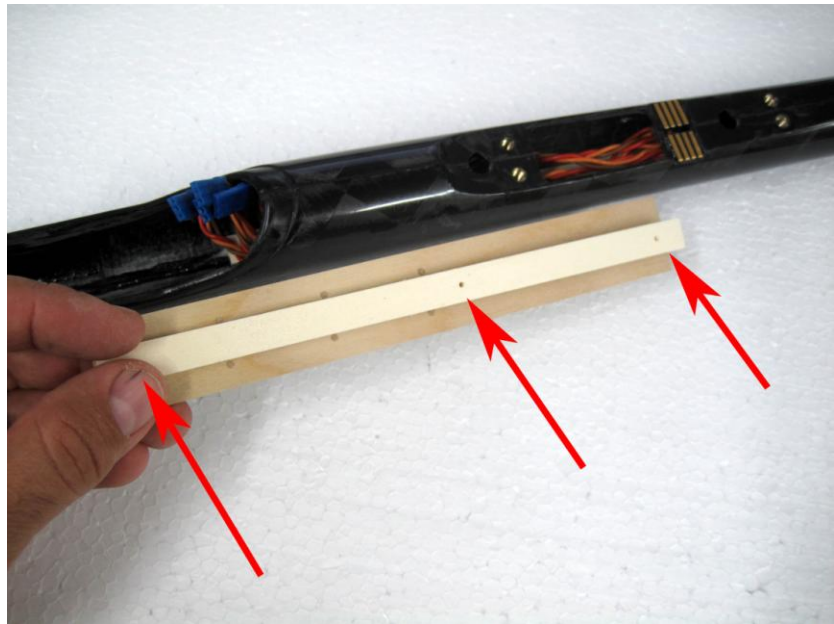
**For both servos: 7mm**

It will be necessary, that you **optimize the lever connector** as shown in the picture beside. Grind free space for the servo axle.

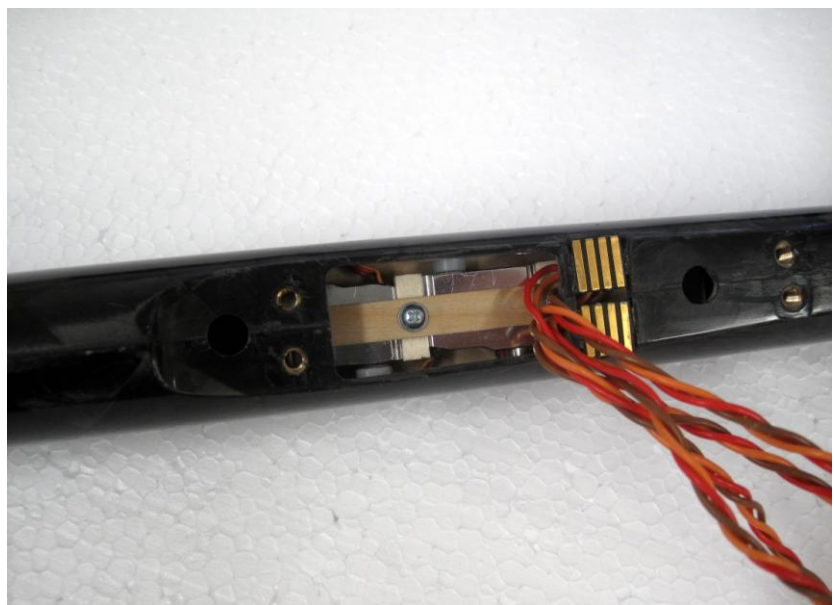


Now screw the **narrow board** to the **bottom** of the servoboard.

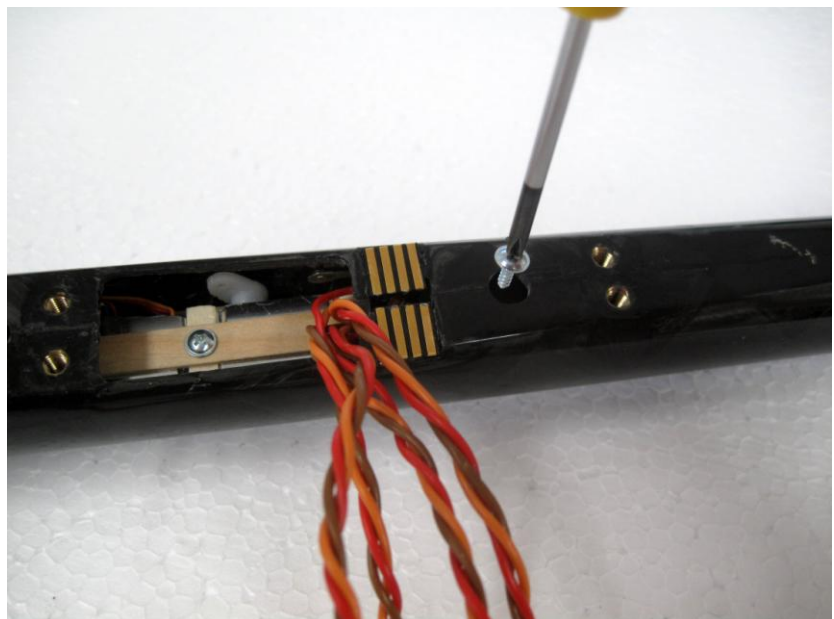
In order to glue it into the fuselage, put a mixture of **epoxy-cottonflocs just onto this narrow board**.



Then put the **servoboard into the fuselage**. **Connect the horns** to the pushrods and set everything to **zero** (servos and control surfaces). Then press the board down to **glue it well** to the bottom.



If you want to change the servos sometime, you can **loosen the screws through the holes in the fuselage**.





## 5.2 Electric drive

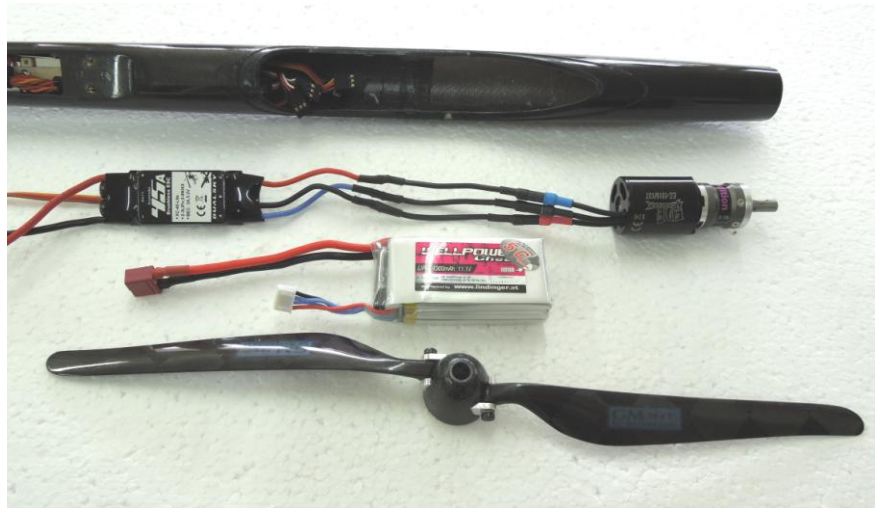
Now **glue the motor mounting** into the fuselage.

Grind a **45° angle** to the edges of the motor mounting and put it **1mm deeper into the fuselage** to get a bigger gluing area.



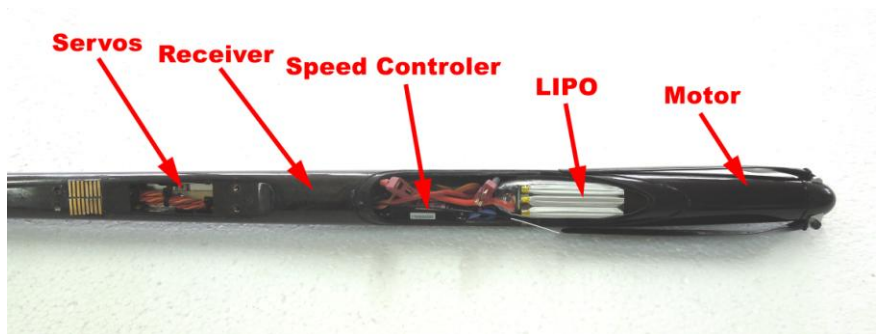
We recommend the following **power set:**

- Tenshock EDF TS-EZ1515 - 13T - 4pol 4200KV with Micro Edition 5:1NL
- 1300mAh 3S Wellpower
- Speed Controller 50A
- Reisenauer 14x7 (2,4kg thrust!). Prop fits great to the fuselage.
- RFM spinner d=28mm with offset 0°



Here you see **everything installed.**

If you optimize the cable lengths, you win a lot of space to mount something else.

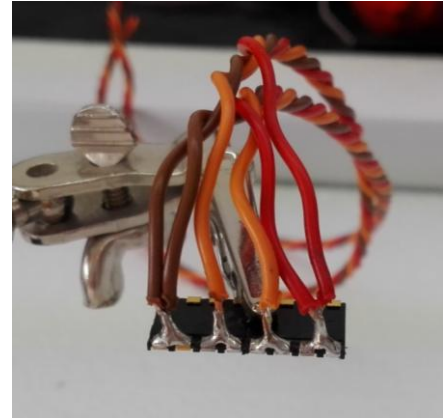
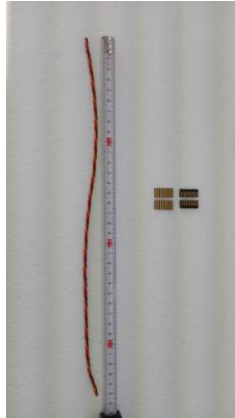


### 5.3 Contacts for flaps and ailerons

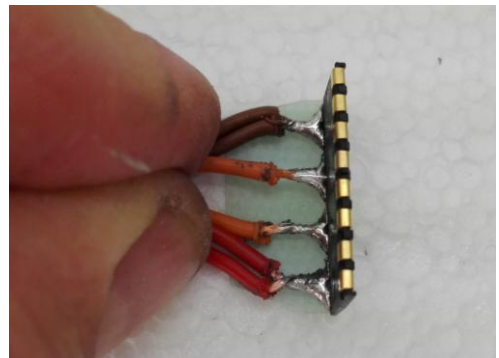
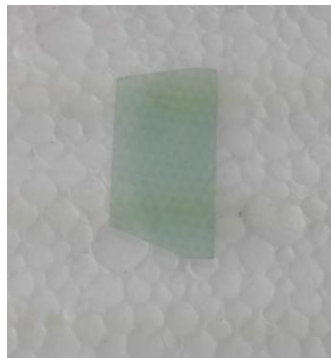
Next, let's finish the **aileron and flap contacts** for the fuselage.

The **cable length** should be about **35cm**. Pay attention that you solder the contacts **in the same way** as they are soldered in the wings.

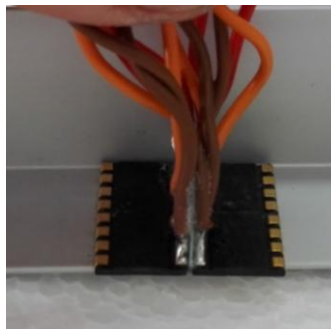
**Double the contacts** again for redundant connection.



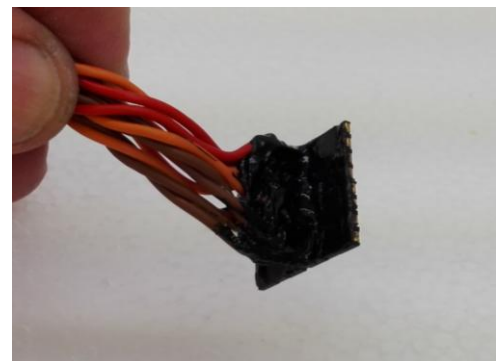
Then glue again a thin piece of GFR to the wirings and the soldered parts. So you **insulate** and **strengthen** the soldered parts.



Now glue the **left** and the **right** cable part together.



The rest of the contacts have to be **insulated**.



Before you fix the contacts to the fuselage with a runny super glue, make a **test, if everything is contacted well**.



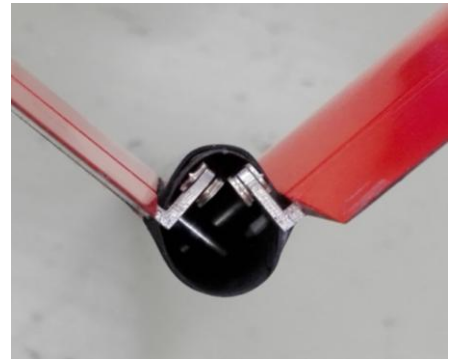


## 5.4 Connection of V-Tail control surfaces and carbon joiners for fuselage connection

Just set the servos and the control surfaces to **zero** and glue the **lever connectors to the pushrods**.

The **black teflon** should be removed before gluing.

**The 6mm carbon rods should be glued into the fuselage.** If you want more transport comfort you could also leave them unglued. But check the fittings before every flight. The fittings should be tight. If they loosen you have to make them tight again with a drop of superglue.



## 5.5 Canopy

We use a very simple solution to mount the canopy. Just **glue the carbon stick** into the canopy. Note that the gluing spot is only **in the middle** of stick and canopy, so you can thread the stick into the fuselage while the canopy remains on the outer side. (here the method is shown on a glass canopy)



## 6. BALLAST

Included in the kit:

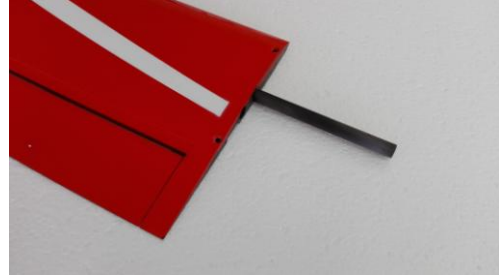
- **2x carbon rod**
- **2x steel rod**

The 2x long steel rods are just delivered if you ask for.

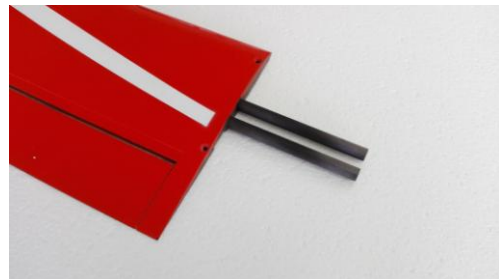


You can use these rods as follows:

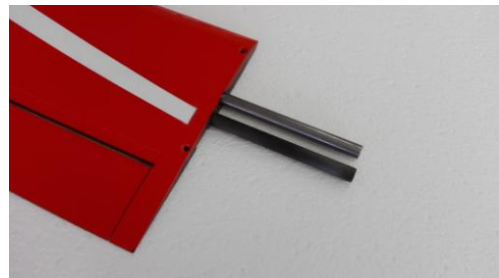
- **1x carbon rod** for **very weak conditions** in the front hole.  
Adjust the CG of the plane with this rod inside. **Don't set full charge on the wing at this configuration.**



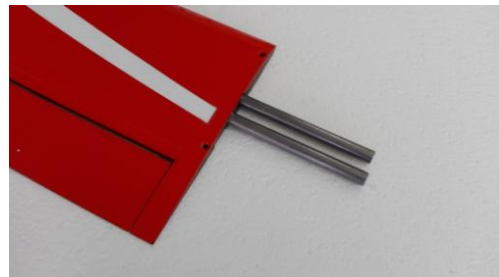
- **2x carbon rods** for **weak conditions**



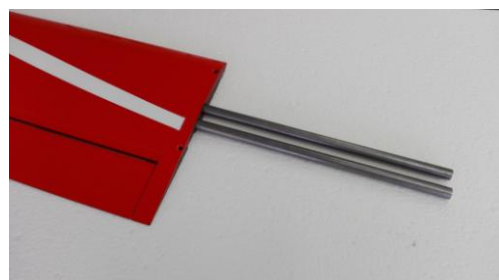
- **1x carbon + 1x steel rod** for **stronger conditions**



- **2x short steel** for **even stronger conditions.**



- **For extra strong conditions** you could insert two 50cm **long steel rods**. That ballast weights **880g** (+836g to the lightest weight).
- When you fly with this setting, you have to take care that you **don't overload the wing structure**. So, use the elevator cautiously, when you fly with that much ballast. Remember also that the landings have to be very soft with such an additional weight.

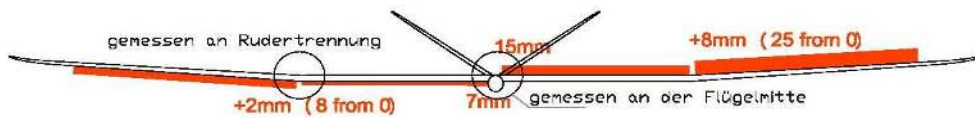


7. SETTINGS FOR FIRST FLIGHT

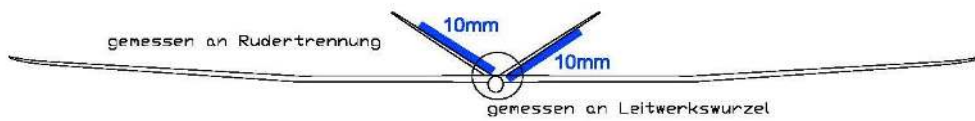
# Recommended CG 86-88mm

CG 85mm for very light conditions (thermaling)

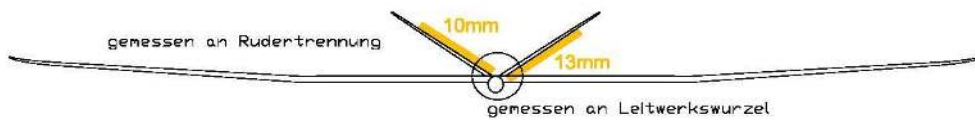
CG 97mm for very strong conditions on a slope



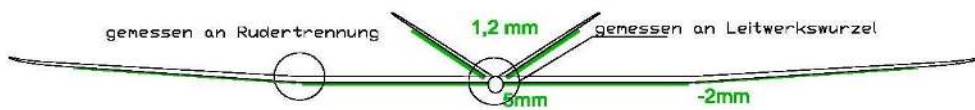
Ail., Flap max



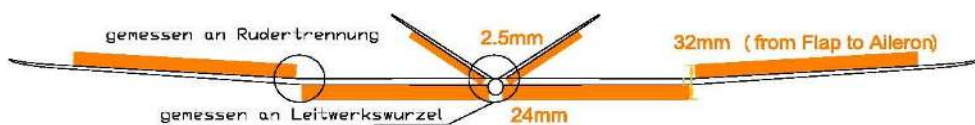
Elevator max



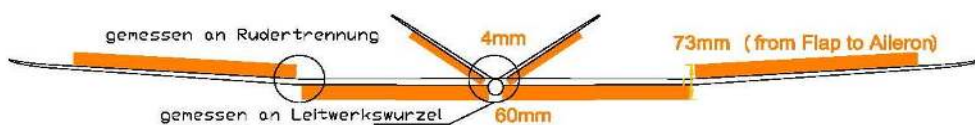
Rudder max



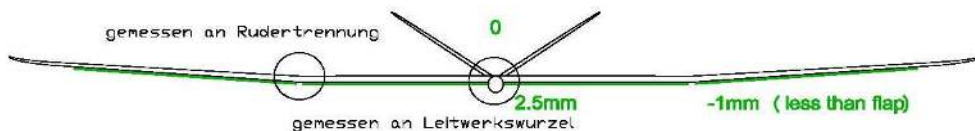
Winch



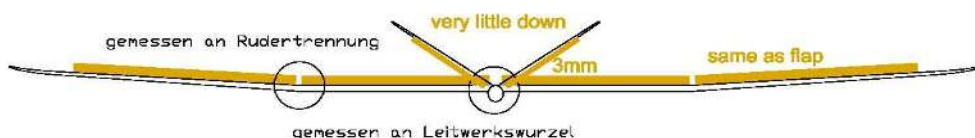
Butterfly half



Butterfly full



Flaps for thermaling



Flaps for speed

## OTHER

### 8. Check list before starting:

1. Check **centre of gravity**
2. Check **control surfaces**:  
Do control surfaces move in the correct direction?  
Check the greatest swings
3. Check **reception**
4. Check **control surfaces before each flight**.  
Do all control surfaces still move correctly?  
Is there enough power in the accumulator?  
Are the brakes retracted?  
You can save the retraction of the brakes in your start setting. By this, you can never start with extended brakes.
5. **Gentle launch** in the flat. If there are some wrong settings, you will realize it during a gentle throw in the flat.

### 9. Notes for the use

To avoid heating of the carbon surface, models with carbon wings should **not lie in the sun**.

**During flight** heating by the sun is no problem, as the model is **cooled by the wind**. **On ground** the glider should be kept **inside protective bags or in the shade**.

After every **ungentle landing**, you must **check your model for possible damage**, such as:

- Is the radio board still glued thoroughly?
- Did the leading edge of the wing burst open?
- Did rudder or elevator get damaged?