Rekon3 FPV Racing Drone

Manual

Contents

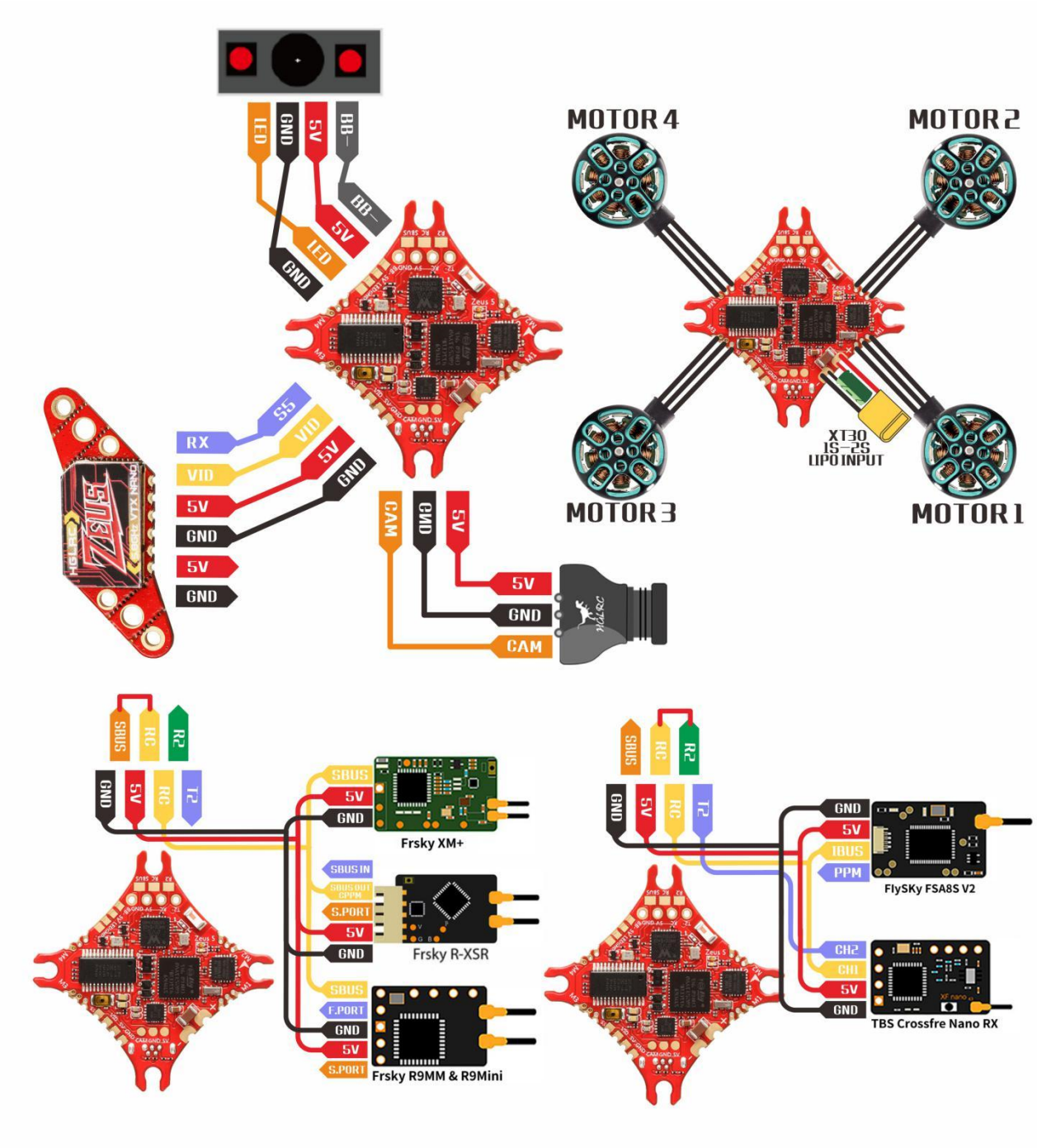
Package Included

HGLRC Rekon3 FPV Racing Drone*1	Accessory Package*1

1.Product Specifications

Product parameters	
Model	Rekon3 VTX FPV Racing Drone
Frame Kit	Rekon3 Frame Kit
Flight Controller	Zeus5 AIO Flight Controller
VTX	Zeus nano 350mW
Motor	1202.5 Motor 1S KV11600
Support Neceiver	SBUS .DSMX.CRSF
Input Voltage	1S Lipo
Weight	62.5g

2.Interface Description

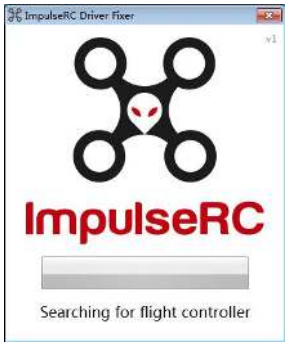


3.Check the flight control drive

1. Long Press BOOT buttons.connect USB.The system automatically install the driver

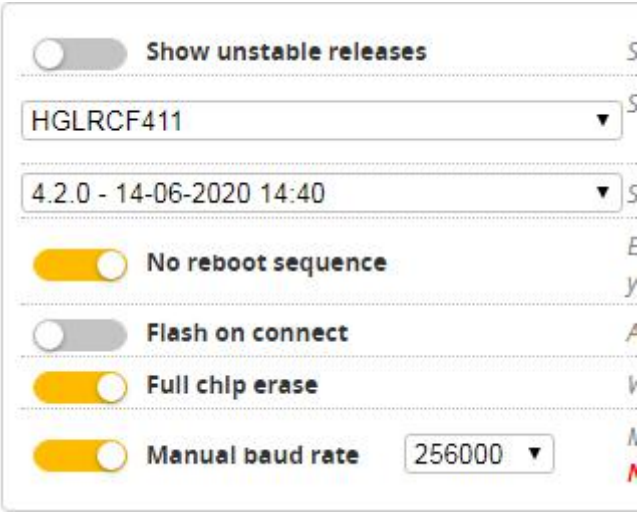
2.Driver cannot be installed, please download ImpulseRC_Driver_Fixer

3.Double-click on the run(Plug in the flight controller to automatically install the driver)



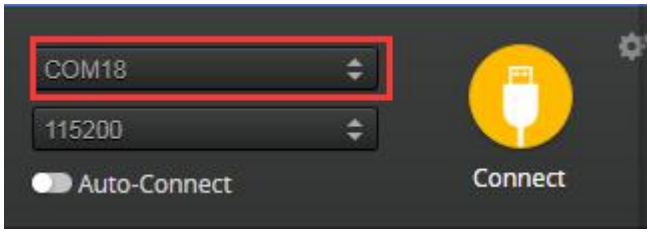
4.open betaflight configurator  , enter DFU mode

5.Click Firmware Flasher Select firmware version



6.Click Load Firmware [Online] Load firmware. Flash Firmware Waiting for completion Erasing ... It will be prompted upon completion. Programming: SUCCESSFUL

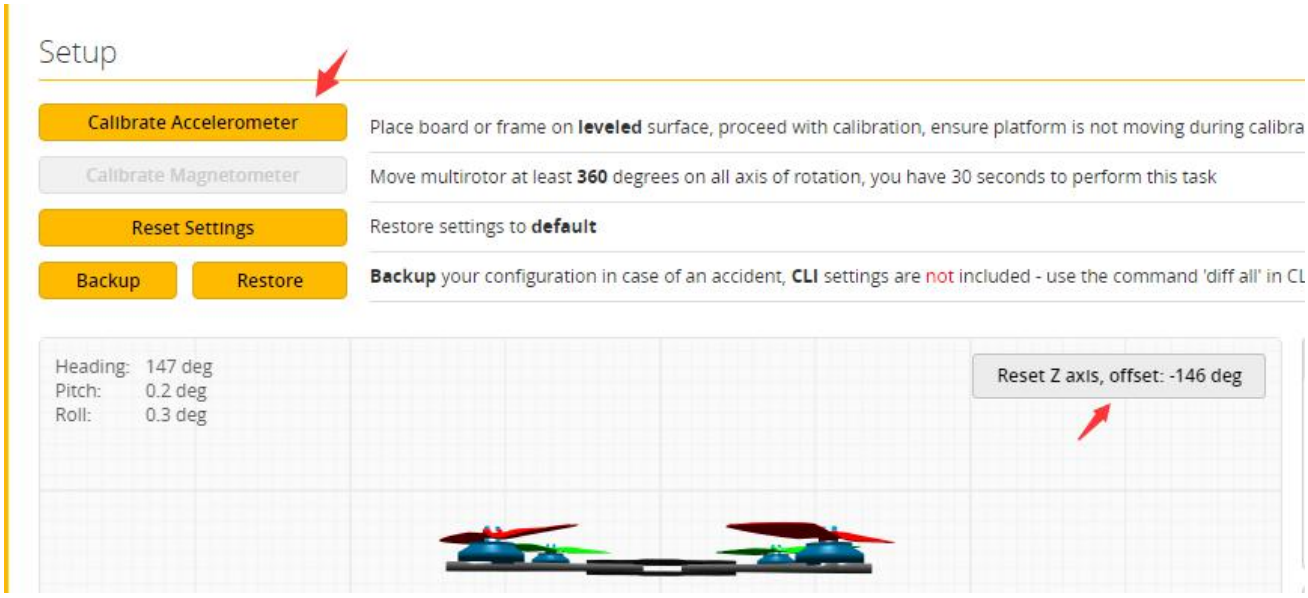
7. open betaflight configurator BETAFLIGHT .Controller plugged into the computer. Betaflight Automatically assigned port, click "Connect" Enter setup interface（Different computer COM）



4. Calibration accelerometer

1. Put the aircraft horizontal and click "Reset Z axis"

Click again Calibrate Accelerometer



5.UART serial port use

1.UART1 uses WIFI

Open WIFI CLI command:

"resource PINIO 1 B10

serial 0 1 115200 57600 0 115200
set pinio_config = 129,1,1,1
set pinio_box = 0,255,255,255

SAVE"

2. UART2 uses receiver

S5 is a soft serial port, dedicated to video transmission (VTX) FM

CLI command of soft serial port:

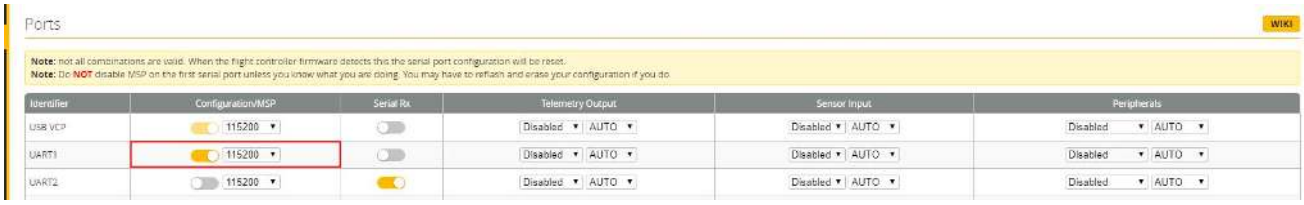
"resource MOTOR 5 none

resource SERIAL_TX 11 B03

SAVE"

6.WIFI function instruciton

1.Click Ports Select Ports



2.Install Speedy Bee on your mobile phone. Connect to WIFI name Started with HermesXXXX.

3.Then click connect to adjust the parameters normally.

4.If the WIFI module light is solid, it means the WIFI is connected to the mobile phone.。

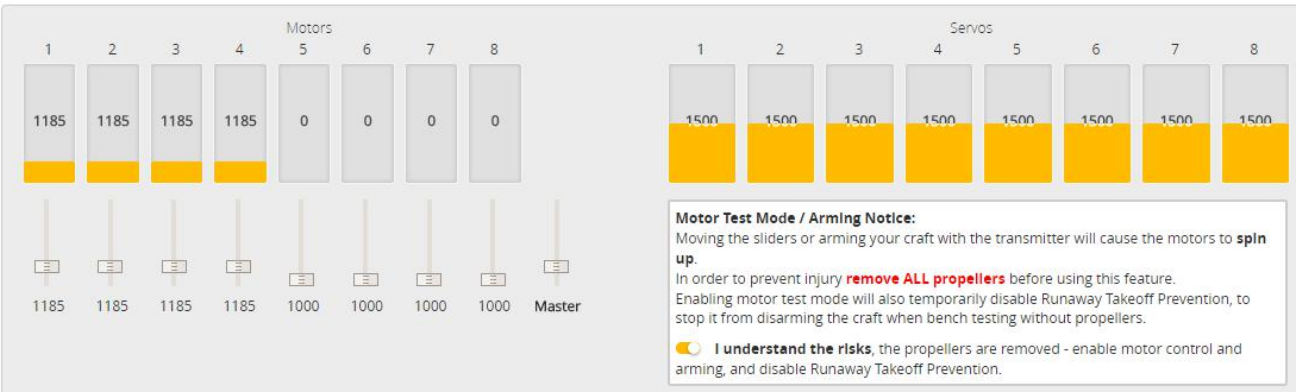
5.If the WIFI module light is solid, but conection is abnormal. Please check your wifi / Speedy Bee settings.

Note: Flight Controller must be powered by battery to connect to WIFI

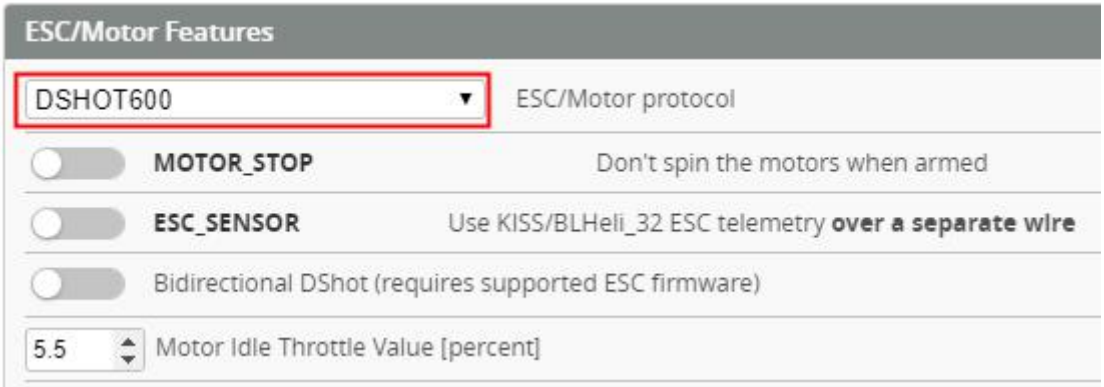
7.Select aircraft model

1.Click Configuration Select model

2.Click Motors Click "I understand the risks" Push Master to check motor steering "Master" Steering can be changed at BLHeliSuite

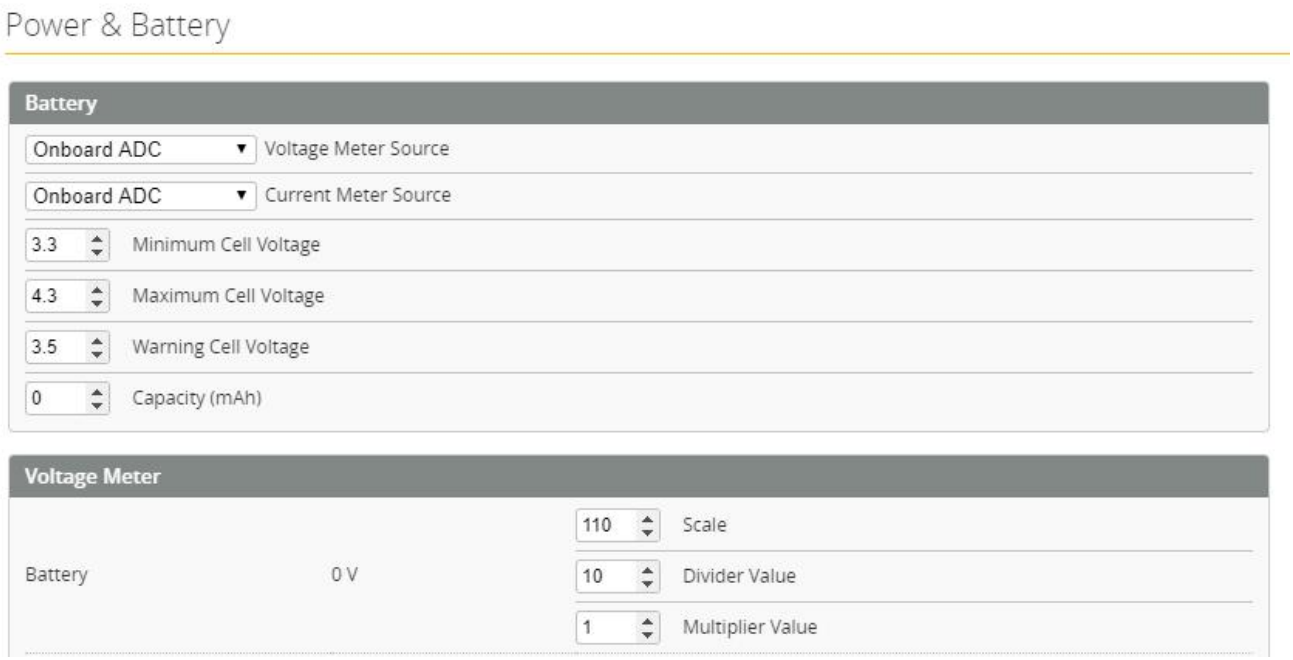


8.Choose ESC protocol



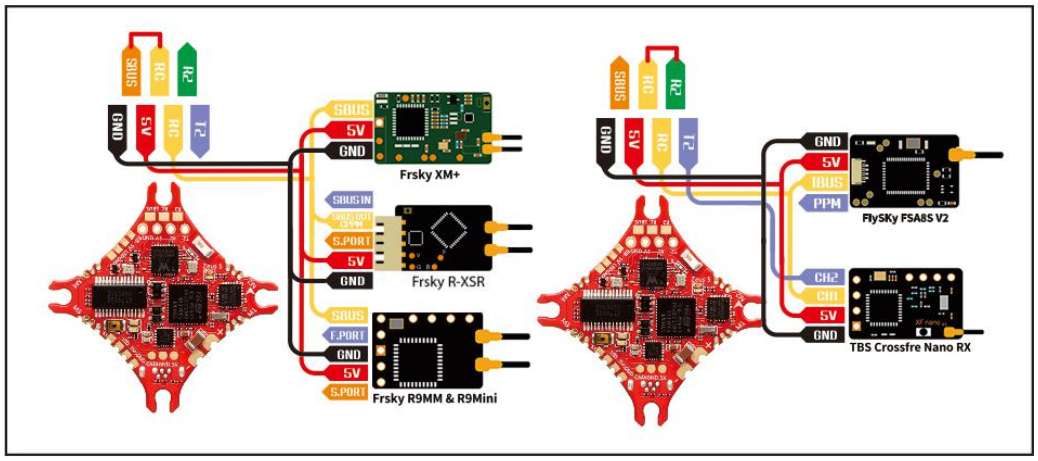
9.Voltage and current parameters setting

1.Click Power & Battery Setting parameters



10.Setting up the receiver

1.Receiver connection diagram



2.Click Ports have found "UART2" Open the receiver serial port

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
SOFTSERIAL1	115200		Disabled AUTO	Disabled AUTO	VTX (IRC Tran AUTO

3.Set the SBUS receiver

Receiver

Serial-based receiver (SPEKSAT, S — Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SBUS — Serial Receiver Provider

4.Set the CRSF receiver

Receiver

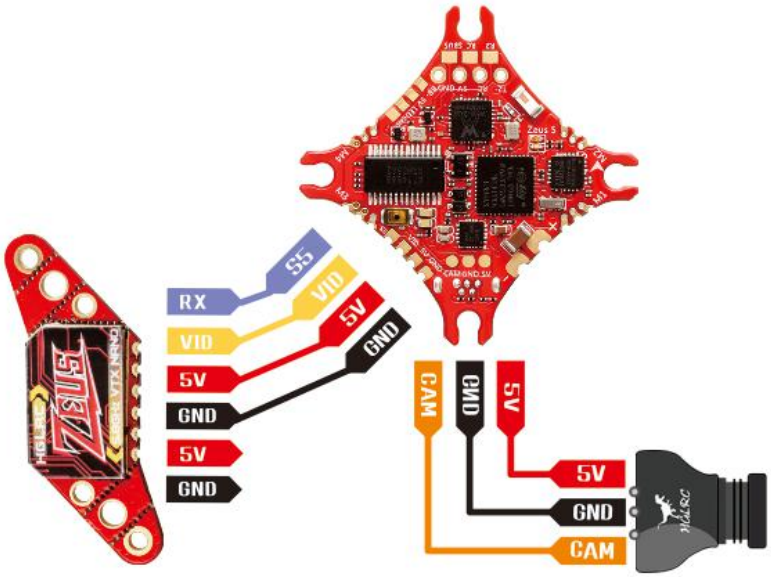
Serial-based receiver (SPEKSAT, S — Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

CRSF — Serial Receiver Provider

11.VTX serial port use wiring

1. 5.8G VTX connection



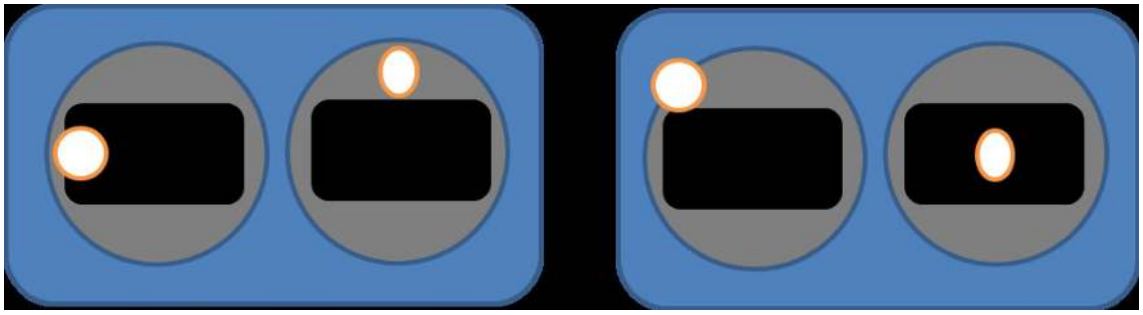
2. 5.8G VTX serial port opens. The protocol is selected according to its own VTX protocol.

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	115200		Disabled AUTO	Disabled AUTO	Disabled AUTO
SOFTSERIAL1	115200		Disabled AUTO	Disabled AUTO	VTX (IRC Tran AUTO

3.Use OSD to adjust VTX

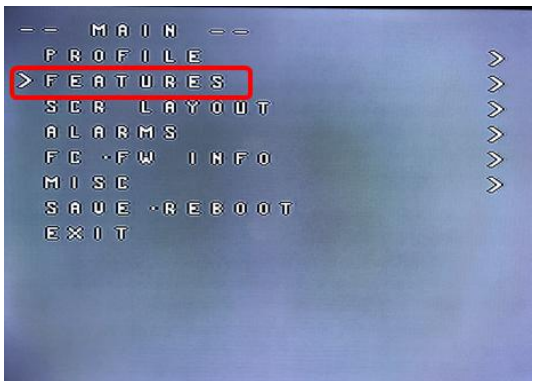
which displays information like battery voltage and mAh consumed while you fly. In addition, the Betaflight OSD can be used to configure the quadcopter, making in-field adjustments and tuning more convenient.

MODE2 MODE1

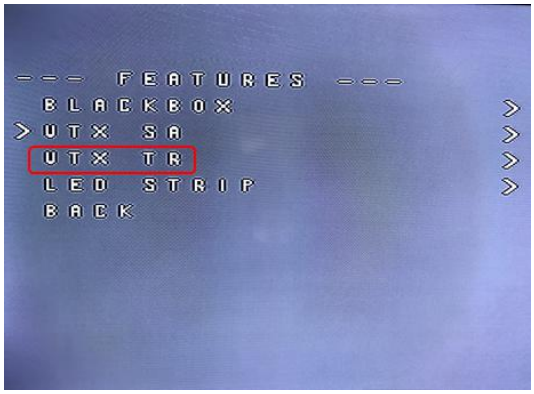


The graphics above show the stick command to bring up the OSD menu. The stick command is: throttle centered, yaw left, pitch forward. The exact stick command therefore depends on which mode your transmitter sticks are in.

In the OSD menu, use pitch up/down to move the cursor between menu items. When a menu option has a > symbol to the right of it, this indicates that it contains a sub-menu. Roll-right will enter the sub-menu. For example, in the screen to the right, moving the cursor to “Features” and then moving the roll stick to the right will enter the “Features” sub-menu.



If you are using a video transmitter that supports remote configuration, enter the “Features” menu to configure the vTX. From there, enter either “VTX SA” if you are using SmartAudio (TBS Unify) or “VTX TR” if you are using IRC Tramp Telemetry.



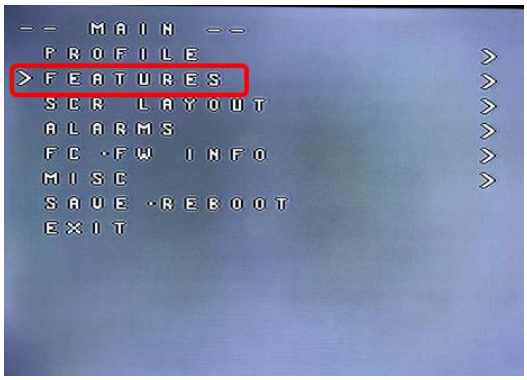
To adjust PIDs, rates, and other tuning-related parameters, enter the “Profile” sub-menu.

In the “Scr Layout” sub-menu, you can move the OSD elements (like battery voltage, mAh, and so forth) around on the screen.

The “Alarms” sub-menu lets you control when the OSD will try to alert you that battery voltage is too low or mAh consumed is too high.

When a parameter can be modified, the parameter’s current value will be shown on the right-hand side of the screen. In this case, roll left/right will adjust the parameter up and down.

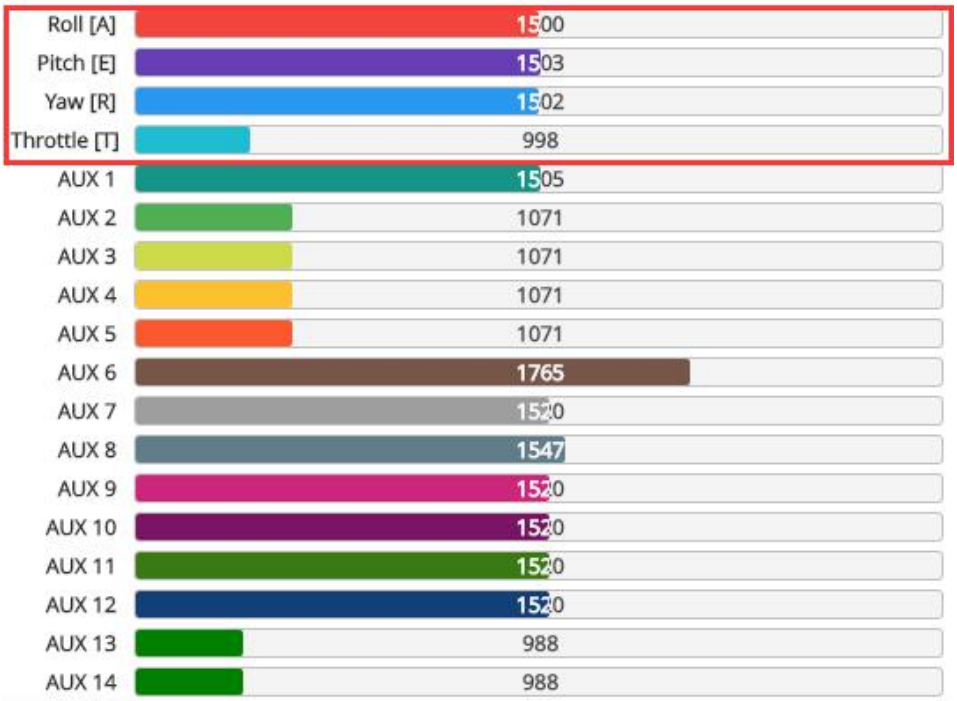
The screen to the right shows the current vTX settings. From here, you can change the frequency band, channel, and power level of the video transmitter. After making the changes, move the cursor to “Set” and press roll-right to confirm the settings.



12.Check receiver signal

1.Click 

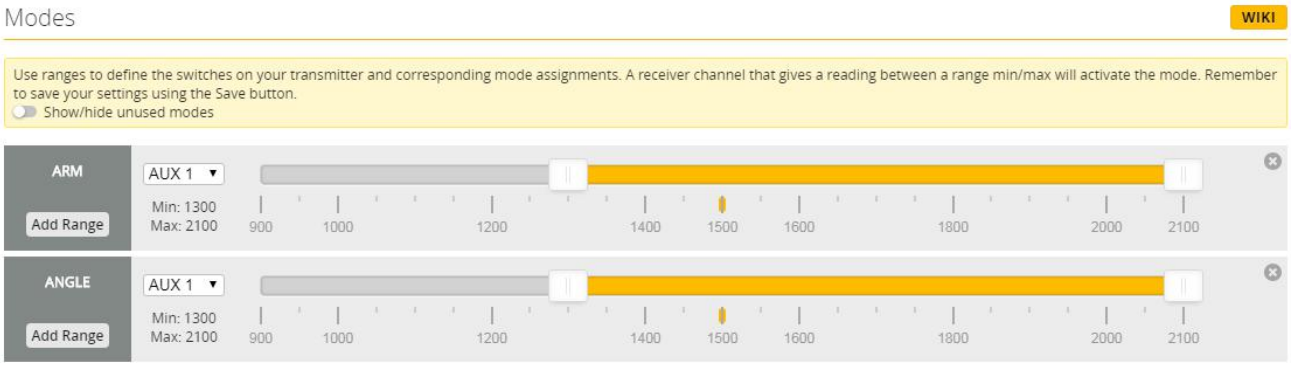
Check the remote control output signal



13.Select flight mode startup mode

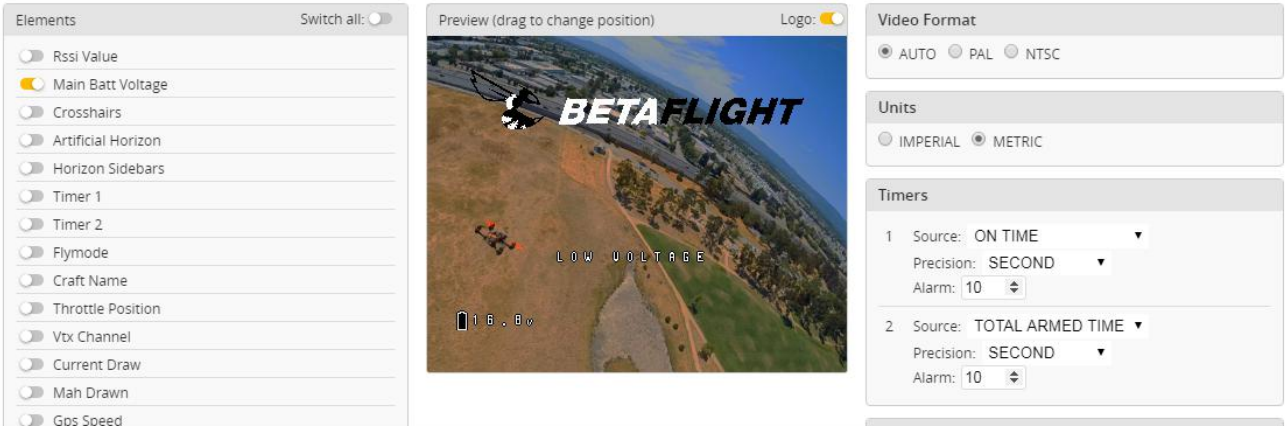
1.Click 

set up the function of remote control switch across the channel (below are for reference only)



14.OSD settings

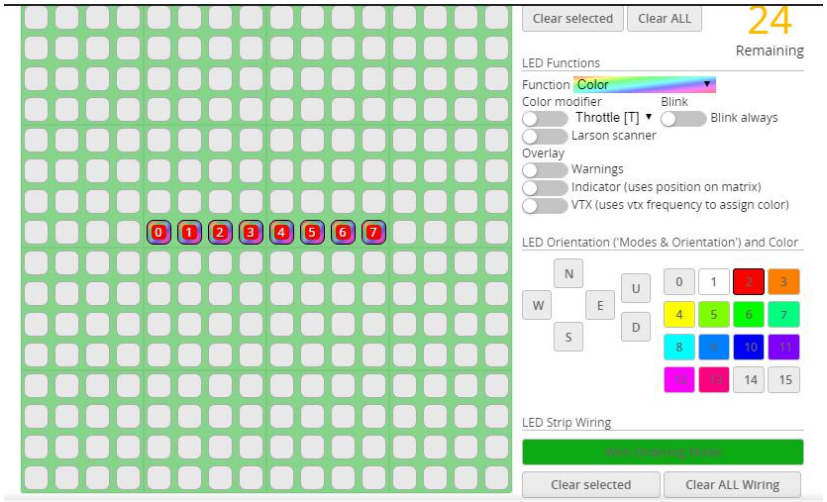
1. Click OSD the OSD Settings, according to the need to choose, drag the OSD schematic diagram of the parameters can be adjusted.



15.LED settings

1.Click Configuration Turn on LED support

2.Click LED Strip .Click Wire Ordering Mode set according to need



16.Troubleshooting

Warning:

Please read the cautions as follows, otherwise stability of your flight controller cannot be ensured, your flight controller will even get damaged.

- Keep focus on the polarity. Check carefully before power supply.
- Cut off the power when you connect, plug and pull anything.
- The refresh rate of PID and Gyroscope is up to 8K/8K.

after sales question:

1. After receiving the goods, it is found that the product can not be used normally. If the return to the factory is a quality problem, the repair service will be provided free of charge.

2. If the product is damaged due to improper operation, the repair service may be provided under the condition that the inspection can be repaired.

3. For domestic customers, please contact the after-sales service personnel. For overseas customers, please contact the official website for after-sales service.

Product daily problems

1.OSD garbled:

If you find garbled characters, please open Betaflight, click “OSD” .and click “Font Manager” clicks on “Upload Font” to update

1. When plugged in the battery, the aircraft does not pass the self-test without "BBB" sound. There is only one sound.

Please check if the ESC agreement is correct

3.The spin of the aircraft keeps spinning

1. Please check if the propeller is correct
2. Please check if the motor direction is correct